

Light Dark Matter Scattering in Gravitational Wave Detectors

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in collaboration with Chun-Hao Lee and Martin Spinrath

Outline

The GW Interferometer

Toy Model for DM Hit

KAGRA

DM Signal at KAGRA

Summary

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Interferometer Used by GW Experiments

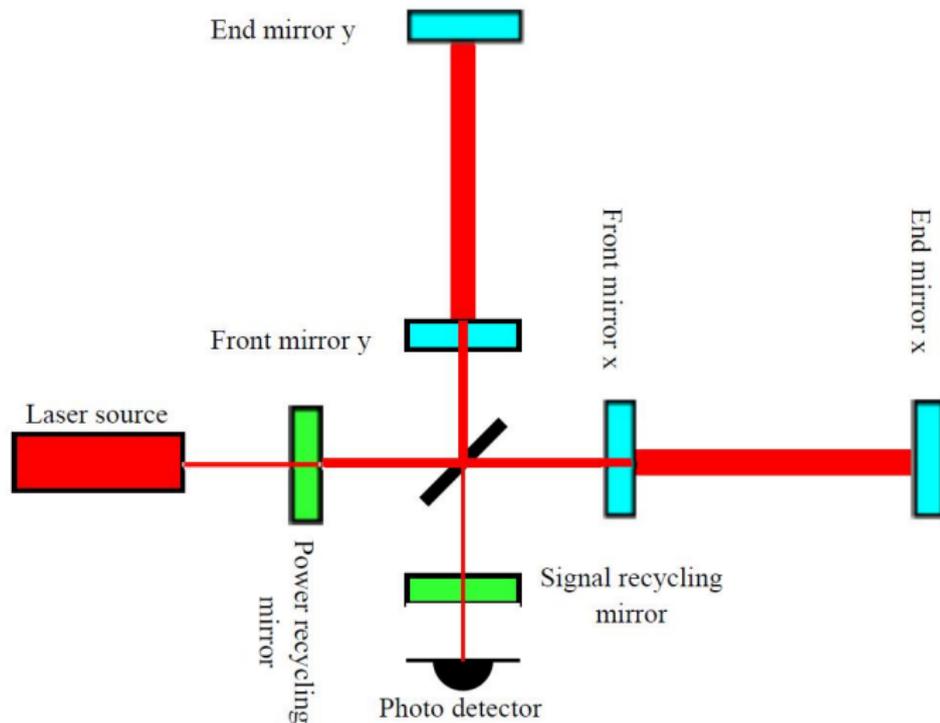


Figure: The interferometer with the arm length (distance between front mirror and end mirror) equals to L . [Taken from KAGRA PhD Thesis: D.Chen, 2016]

- ▶ The change in the interference of the light is proportional to

$$\Delta L = \Delta L_x - \Delta L_y$$

- ▶ A gravitational wave will induce a strain, h_{GW}

$$h_{\text{GW}} \sim \frac{\Delta L}{L} \leq 10^{-20}$$

- ▶ What about strain induced by DM ?
- ▶ Is it visible compared to the noises? What noises?

Strain Amplitude Budgets

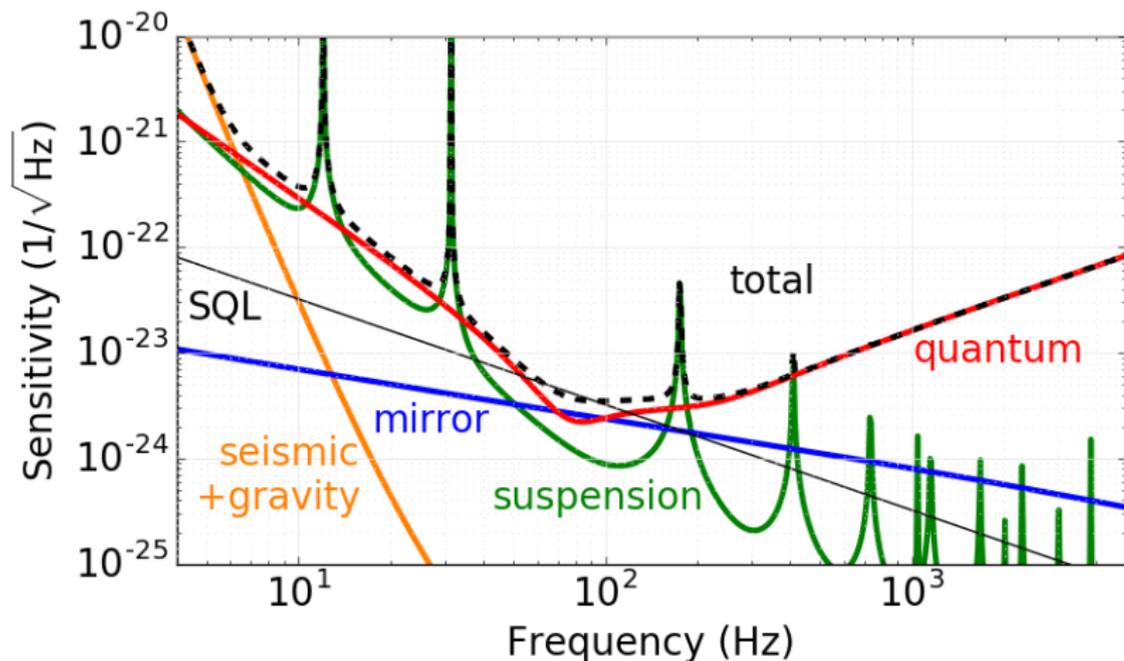


Figure: Example of the strain amplitude of the noises.

[<https://gwcenter.icrr.u-tokyo.ac.jp/en/researcher/parameter>]

Interferometer Isolation

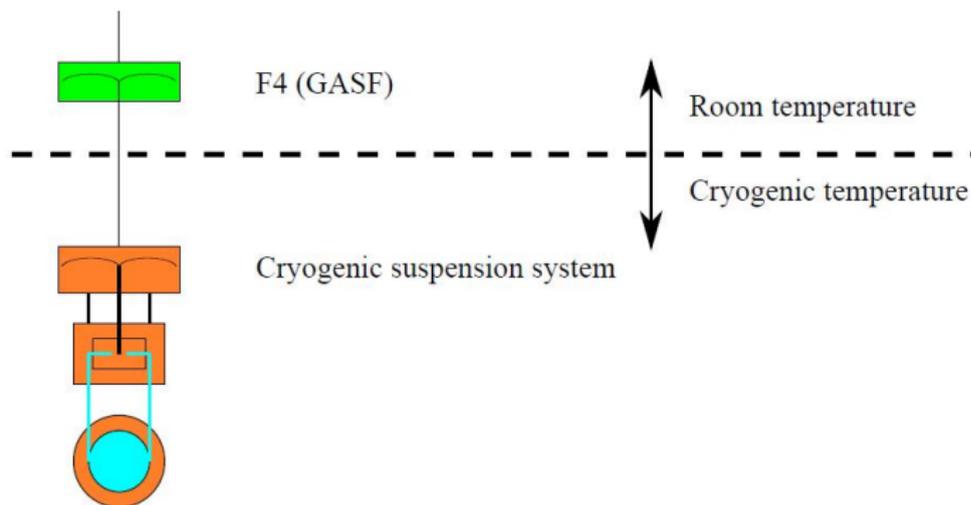


Figure: Schematic of the interferometer isolation. [Taken from KAGRA PhD Thesis: D.Chen, 2016]

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Toy Model to Estimate DM Induced Strain

- ▶ Simple pendulum describing the TM and its suspension system

$$m\ddot{x}_c + k_c(1 + i\phi)x_c = \frac{F_{\text{ext},c}}{L}$$

- ▶ We model the total displacement [Moore, Cole, Berry '14]

$$x_{\text{tot},c}(t) = x_{\text{th},c}(t) + x_{\text{qu},c}(t) + x_{\text{DM},c}(t)$$

- ▶ The strain can be obtained from one-sided power spectral density (PSD)

$$h_i(\omega) = \sqrt{S_i(\omega)}$$

Suspension Thermal Noise

- ▶ According to fluctuation-dissipation theorem, the thermal noise PSD is given by [Callen, Welton '51]

$$S_{\text{th}}(\omega) = \frac{4k_B T}{L^2 \omega^2} \Re[Y(\omega)]$$

- ▶ The admittance for $F_{\text{ext}} \sim \exp(i\omega t)$ in this case

$$Y(\omega) \equiv \frac{\dot{x}_{\text{th},c}}{F_{\text{ext}}/(mL)} = i\omega D_c^{-1}(\omega) = \frac{i\omega}{(-m\omega^2 + k_c(1 + i\phi))}$$

- ▶ $D_c(\omega)$ is the Fourier transform of the differential operator.

- ▶ The Thermal noise PSD of the Toy model ($\omega_c^2 \equiv k_c/m$)

$$S_{\text{th},c}(\omega) = \frac{4k_B T}{L^2} \frac{\phi \omega_c^2 / (m\omega)}{(\omega^2 - \omega_c^2)^2 + \omega_c^4 \phi^2}$$

- ▶ The associate Thermal noise strain

$$h_{\text{th}}(\omega) = \sqrt{S_{\text{th}}(\omega)}$$

- ▶ For quantum noise, we use the standard quantum limit (SQL)

$$S_{\text{qu}}(\omega) = \frac{8\hbar}{m\omega^2 L^2}$$

- ▶ The corresponding strain

$$h_{\text{qu}}(\omega) = \sqrt{S_{\text{qu}}(\omega)}$$

- ▶ The total noise reads

$$h_{\text{n}}(\omega) = \sqrt{h_{\text{th}}^2(\omega) + h_{\text{qu}}^2(\omega)}$$

- ▶ Recall the simple pendulum motion

$$m \ddot{x}_{\text{DM}} + k_c(1 + i\phi) x_{\text{DM}} = \frac{F_{\text{ext}}}{L}$$

- ▶ Using Fourier expansion

$$g(t) = \int_{-\infty}^{\infty} d\omega \tilde{g}(\omega) e^{i\omega t}$$

- ▶ We assume single DM hit at $t = 0$ [Lee, Nugroho, MS '20; Tsuchida et al.'19]

$$F_{\text{ext}}(t) = q_R \delta(t)$$

- ▶ The displacement induced by DM in frequency domain reads

$$\tilde{x}_{\text{DM}}(\omega) = \frac{q_R}{mL} \frac{1}{(-\omega^2 + \omega_c^2(1 + i\phi))}$$

- ▶ The DM induced strain

$$h_{\text{DM}}(\omega) = \sqrt{\frac{2\omega}{\pi}} |\tilde{x}_{\text{DM}}(\omega)|$$

The Strain for the Toy Model

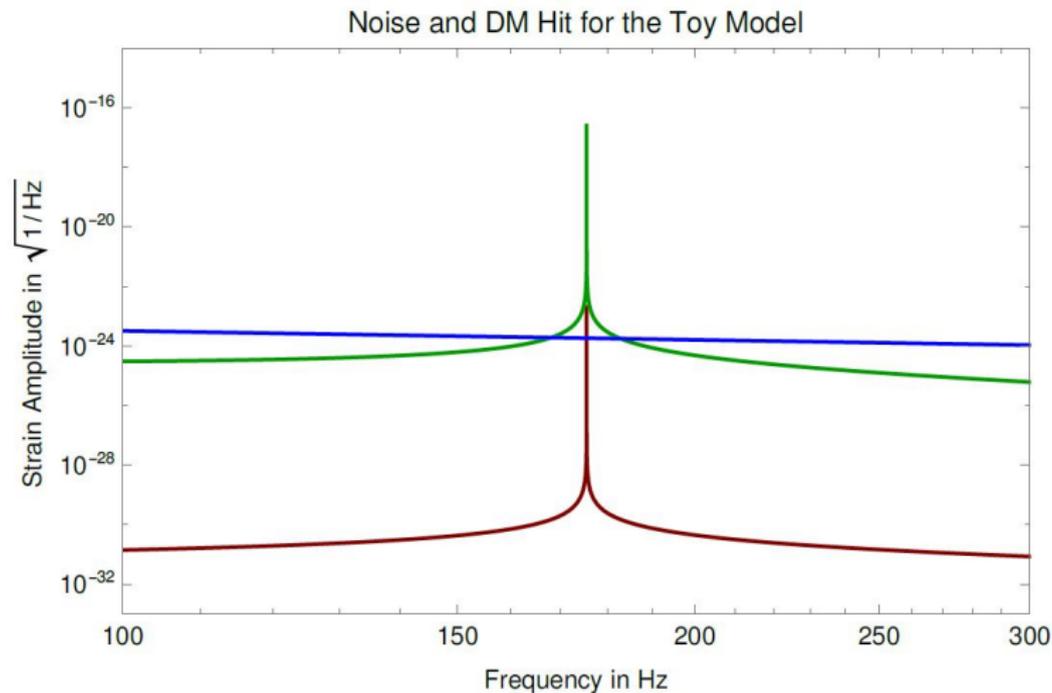


Figure: **Thermal noise**, **SQL**, **DM Signal**.

Signal to Noise Ratio (SNR)

- ▶ The optimal SNR [Moore, Cole, Berry '14]

$$\varrho^2 = \int_{f_{\min}}^{f_{\max}} df \frac{4 |\tilde{x}_{DM}(2\pi f)|^2}{S_n(2\pi f)}$$

- ▶ For: $f_0 = 175.4$ Hz, $\phi = 6.32 \times 10^{-12}$, $m = 22.8$ kg, $T = 19$ K, $L = 3$ km, $m_{DM} = 1$ GeV/ c^2 , and $|\vec{v}_{DM}| = 220$ km/s
- ▶ Around the peak at full width half maximum (FWHM)

$$\varrho_{\text{th}}^2 = \frac{1}{2\pi} \frac{q_R^2}{m k_B T} = \frac{1}{2\pi} \frac{E_R}{E_{\text{th}}} = 4.09 \times 10^{-24}$$

- ▶ $E_R = 3.37 \times 10^{-45}$ J and $E_{\text{th}} = 1.31 \times 10^{-23}$ J
- ▶ Lighter mirror and colder for better SNR.

Outline

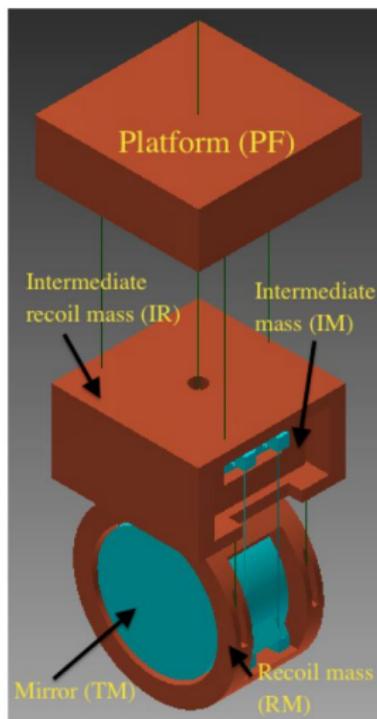
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Summary



- ▶ KAGRA is GW detector currently running in Japan
- ▶ Equipped with cryogenic system with mirror temperature around 20 K
- ▶ The suspension system is modelled as triple pendulum consist of: IM, Blade Springs, and TM

Figure: [KAGRA PhD Thesis: D.Chen, 2016]

- ▶ Vertical suspension thermal noise [KAGRA Document, JGW-T1707038v9]

$$\left(M \frac{d^2}{dt^2} + K_v \right) \vec{x}_v(t) = \frac{\vec{F}_{\text{ext},v}(t)}{L}$$

$$M = \begin{pmatrix} m_1 & 0 & 0 \\ 0 & m_2 & 0 \\ 0 & 0 & m_3 \end{pmatrix}, \quad K_v = \begin{pmatrix} K_{1v} + K_{2v} & -K_{2v} & 0 \\ -K_{2v} & K_{2v} + K_{3v} & -K_{3v} \\ 0 & -K_{3v} & K_{3v} \end{pmatrix}$$

$$\vec{x}_v(t) = \begin{pmatrix} x_{1v}(t) \\ x_{2v}(t) \\ x_{3v}(t) \end{pmatrix} \quad \text{and} \quad \vec{F}_{\text{ext},v}(t) = \begin{pmatrix} F_{\text{ext},1v}(t) \\ F_{\text{ext},2v}(t) \\ F_{\text{ext},3v}(t) \end{pmatrix}.$$

$$K_{iv} \equiv k_{iv}(1 + i\phi_{iv})$$

- ▶ The index $i = (1, 2, 3)$ stands for (IM, BS, and TM)

KAGRA Suspension Thermal Noise

- ▶ The equation in frequency domain

$$D_v(\omega)\vec{x}_v \equiv (-\omega^2 M + K_v)\vec{x}_v = \frac{\vec{F}_{\text{th},v}}{L}$$

- ▶ The vertical admittance reads

$$Y_v(\omega) \equiv i\omega D_v^{-1}(\omega)$$

- ▶ Thermal noise PSD of the vertical thermal noise

$$S_{\text{th},v}(\omega) = \frac{4 k_B T \Re(Y_v(\omega))_{33}}{L^2 \omega^2}$$

- ▶ The strain amplitude of vertical suspension thermal noise

$$h_{\text{th},v}(\omega) = \text{VHC} \sqrt{4 |S_{\text{th},v}(\omega)|}$$

- ▶ VHC due to the tilt of the baseline. Its value is $\frac{1}{200}$

- ▶ Horizontal thermal noise proceed in similar manner as the vertical one
- ▶ Mirror thermal noise and quantum noise
- ▶ Sum over the total noise

$$h_{\text{tot}}(\omega) = \sqrt{h_{\text{th},v}^2 + h_{\text{th},h}^2 + h_{\text{qu}}^2(\omega) + h_{\text{mir}}^2(\omega)}$$

KAGRA Noise

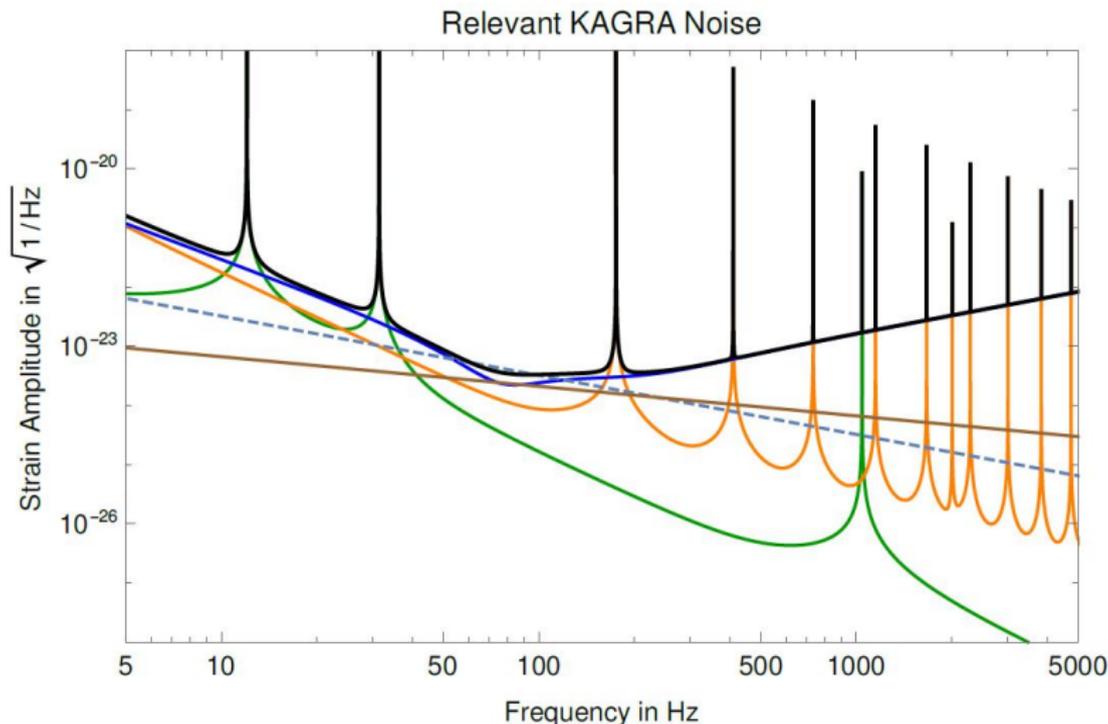


Figure: total noise: **vert.susp.**, **horz.susp.**, **mirror noise**, **quantum noise** (solid blue), and **SQL** (dashed blue) [Lee, Nugroho, MS '20; JGW-T1707038v9]

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- ▶ DM hit the j -th component from vertical direction [Lee, Nugroho, MS '20]

$$F_{\text{DM},jv}(t) = q_{R,jv}\delta(t)$$

- ▶ The Fourier transform of the displacement of the i -th component

$$\tilde{x}_{iv}(\omega) = \sum_{j=1}^3 (D_v^{-1}(\omega))_{ij} \frac{\tilde{F}_{j,v}(\omega)}{L}$$

- ▶ Since we probe the third component, we have

$$|\tilde{x}_{\text{DM},v}(\omega)|^2 \equiv |\tilde{x}_{3v}(\omega)|^2 = \left| \sum_{j=1}^3 (D_v^{-1}(\omega))_{3j} \frac{\tilde{F}_{j,v}(\omega)}{L} \right|^2$$

- ▶ The strain is given by

$$h_{\text{DM},v}(\omega) = \text{VHC} \sqrt{\frac{2\omega}{\pi} |\tilde{x}_{\text{DM},v}(\omega)|^2}$$

- ▶ The DM induced strain in horizontal direction

$$h_{\text{DM},v}(\omega) = \sqrt{\frac{2\omega}{\pi}} |\tilde{\chi}_{\text{DM},h}(\omega)|^2$$

- ▶ The total DM signal

$$|\tilde{\chi}_{\text{DM}}(\omega)|^2 = \text{VHC}^2 |\tilde{\chi}_{\text{DM},v}(\omega)|^2 + |\tilde{\chi}_{\text{DM},h}(\omega)|^2$$

DM Signal at KAGRA

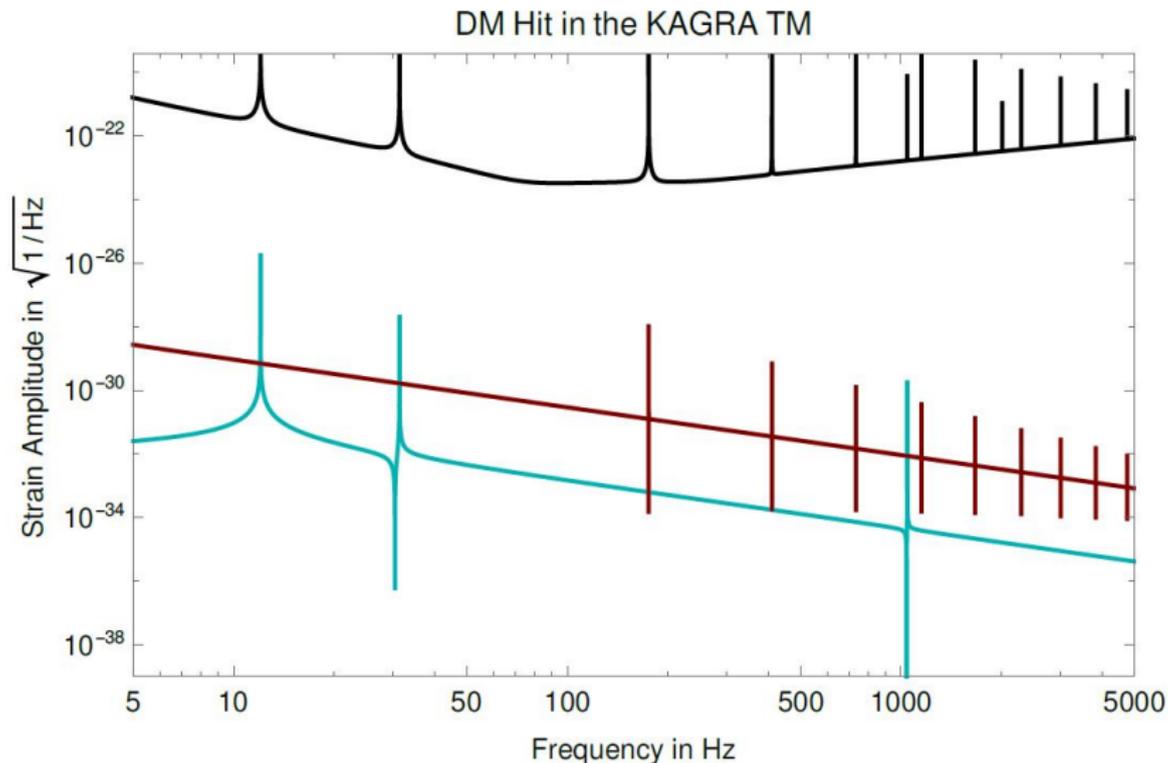


Figure: total noise, DM vertical hit, and DM horizontal hit

DM Signal at KAGRA

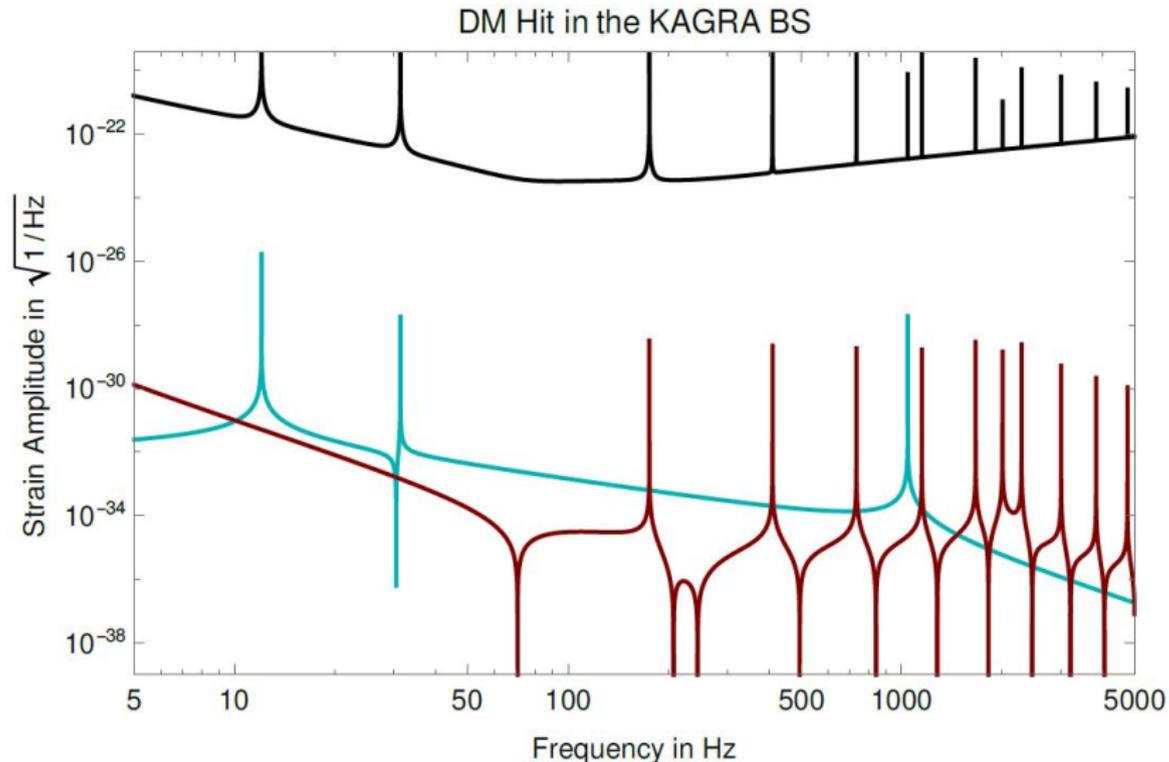


Figure: total noise, DM vertical hit, and DM horizontal hit

DM Signal at KAGRA

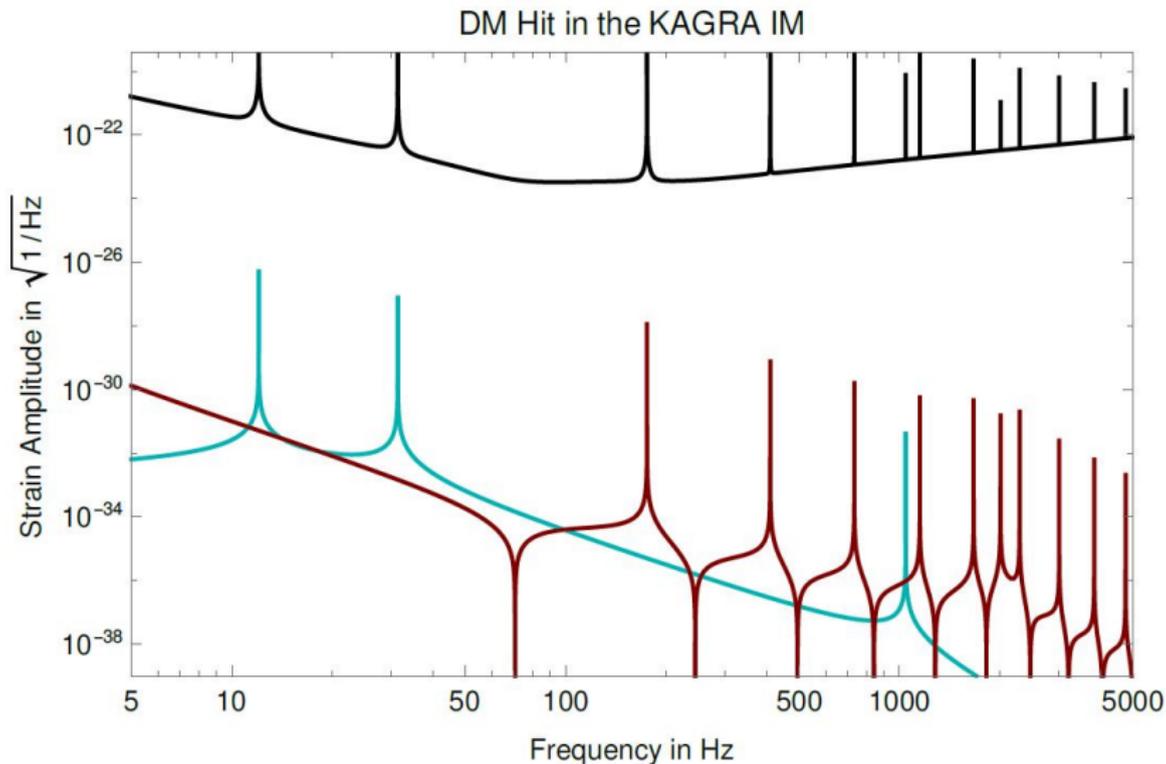


Figure: **total noise**, **DM vertical hit**, and **DM horizontal hit**

- ▶ For horizontal DM hit

$$\varrho_h^2 = \int_{f_{\min,h}}^{f_{\max,h}} df \frac{4|\tilde{\chi}_{\text{DM}}(2\pi f)|^2}{S_{\text{tot}}(2\pi f)}$$

- ▶ We integrate around the peak which is located at 175.4 Hz

$$f_{\min,h} = 170\text{Hz} \text{ and } f_{\max,h} = 180\text{Hz}$$

- ▶ This gives the SNR

$$\varrho_h^2 = 6.94 \times 10^{-18}$$

- ▶ For vertical hit around 31.4 Hz

$$f_{\min,h} = 30.4\text{Hz} \text{ and } f_{\max,h} = 32.4\text{Hz}$$

- ▶ The corresponding SNR

$$\varrho_v^2 = 1.89 \times 10^{-21}$$

- ▶ LISA path finder sensitivity within $0.1 \text{ mHz} \leq f \leq 30 \text{ Hz}$ [LISA Pathfinder '16]

$$\sqrt{S_{\Delta g}} \leq 3\sqrt{2} \text{ fm s}^{-2}/\sqrt{\text{Hz}} \times \sqrt{1 + (f/8 \text{ mHz})^4}$$

- ▶ DM induced strain

$$\sqrt{S_{\Delta g, \text{DM}}} \sim 4.1 \times 10^{-7} \sqrt{\frac{f}{\text{Hz}}} \text{ fm s}^{-2}/\sqrt{\text{Hz}}$$

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- ▶ The current interferometer used in GW experiments are very sensitive.
- ▶ DM can excite mechanical resonance as suspension thermal noise does.
- ▶ For DM detection, lighter and colder mirror are needed.
- ▶ LPF is quite sensitive, but not sensitive enough to detect DM.